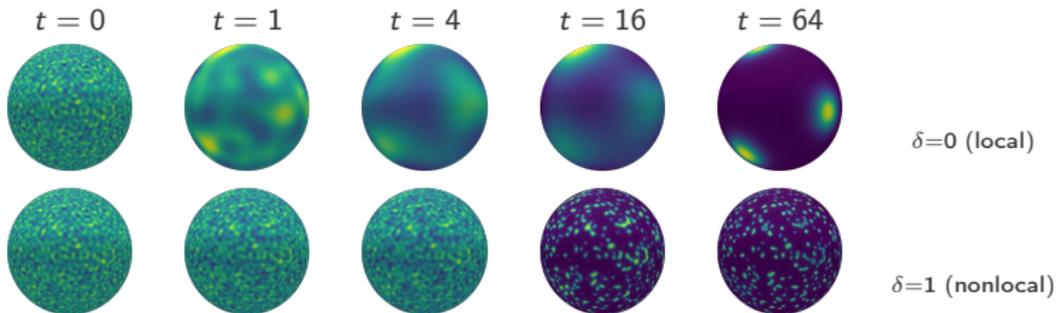


Fourth-order time-stepping for PDEs on the sphere—and more

École Polytechnique & INRIA – DEFI Internal Seminar

Hadrien Montanelli

& Q. Du, Y. Nakatsukasa, M. Slevinsky, S. Shvartsman, N. Trefethen



- Reaction-diffusion equations¹

$$\begin{cases} u_t = \epsilon_u^2 \Delta u + F(u, v), \\ v_t = \epsilon_v^2 \Delta v + G(u, v) \end{cases}$$

- Pray-predator system (time)

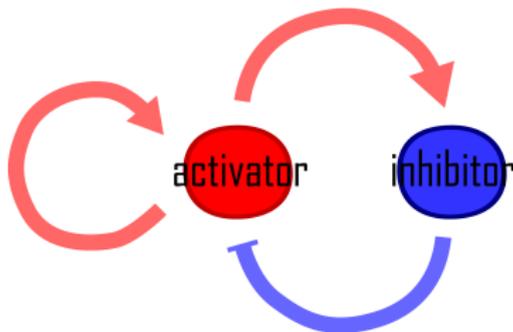
activator versus inhibitor

activator—stimulates production

inhibitor—slows production down

- Notion of spreading rate (space)

- Spherical geometry: embryogenesis, growth of tumors, convective patterns



¹Turing, *The chemical basis of morphogenesis* (1952)

- **Problem:** Computing solutions of local and nonlocal PDEs of the form

$$u_t(t, \theta, \varphi) = \epsilon^2 \mathcal{L}_\delta u + \mathcal{N}(u), \quad (\theta, \varphi) \in \times [0, \pi] \times [-\pi, \pi]$$

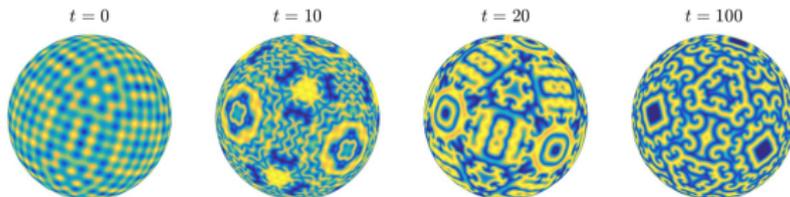
- **Method:** expand u in a spectral basis & time-stepping on expansion coefficients

- **Local PDEs:** 2D Fourier series & implicit-explicit schemes

My contribution: a spectral method

- **Nonlocal PDEs:** spherical harmonics & exponential integrators

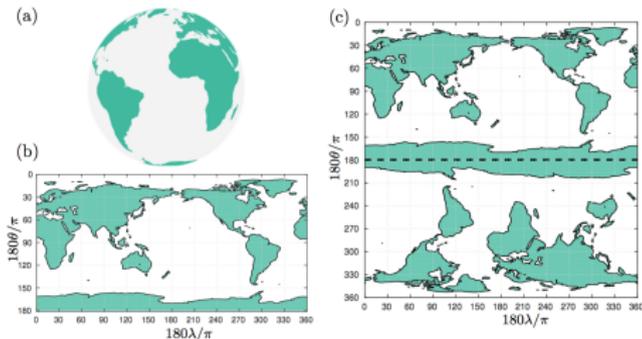
My contributions: def. nonlocal diffusion operator & a spectral method



$\delta=0$ (local)

■ Local PDEs:

$$u_t = \epsilon^2 \Delta u + \mathcal{N}(u), \quad \Delta u = u_{\theta\theta} + \frac{\cos \theta}{\sin \theta} u_\theta + \frac{1}{\sin^2 \theta} u_{\varphi\varphi}$$

 ■ Double Fourier Sphere method (Merilees, Orszag, Townsend et al.²)

 ■ Approximations by 2D Fourier series with $N = n^2$ coeffs:

$$u(t, \theta, \varphi) \approx \sum_{\ell=-n/2}^{n/2-1} \sum_{m=-n/2}^{n/2-1} \hat{u}_{\ell m}(t) e^{i(\ell\theta + m\varphi)}, \quad \hat{u}_{\ell, m} = \hat{u}_{-\ell, m}(-1)^m$$

²Townsend, Wilber & Wright, *Computing with functions in spherical and polar geometries* (2016)

- Operator Δ discretized with a $N \times N$ matrix \mathbf{L} acting on Fourier coefficients \hat{u}

- PDE $u_t = \epsilon^2 \Delta u + \mathcal{N}(u) \rightarrow$ system of ODEs $\hat{u}'(t) = \epsilon^2 \mathbf{L} \hat{u} + \mathbf{N}(\hat{u})$

- Method for constructing \mathbf{L} :³

standard Fourier matrices

projection matrices

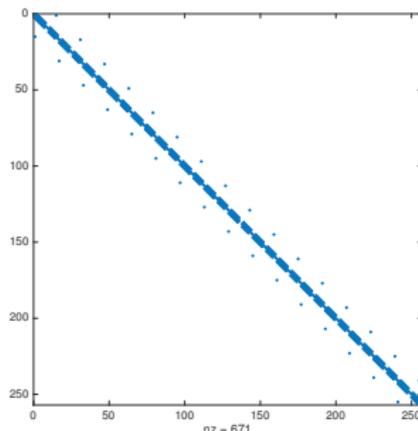
- \mathbf{L} has good numerical properties:

preserves *doubled-up symmetry*

preserves *smoothness at the poles*

has *real and negative eigenvalues*

can be inverted in $\mathcal{O}(N)$ operations



³M. & Nakatsukasa, *Fourth-order time-stepping for PDEs on the sphere* (2018)

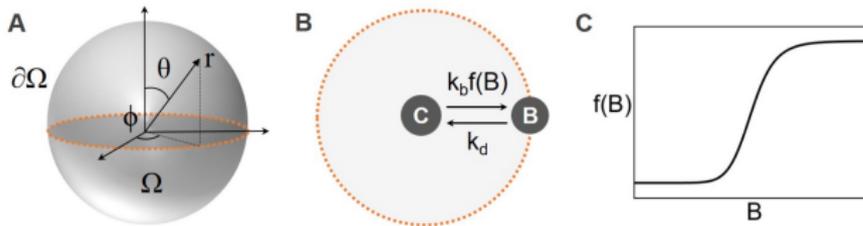
- PDE $u_t = \epsilon^2 \Delta u + \mathcal{N}(u) \rightarrow$ system of ODEs $\hat{u}'(t) = \epsilon^2 \mathbf{L} \hat{u} + \mathbf{N}(\hat{u})$

- Discretization with time-step Δt : $\hat{u}^k = \hat{u}(k\Delta t)$, $k = 0, 1, \dots$
- Large $\mathcal{O}(N^2)$ eigenvalues: stiffness, standard explicit time-stepping impractical

- Implicit-explicit (Ascher et al.⁴): implicit formula for \mathbf{L} , explicit for \mathbf{N}
$$(\mathbf{3I} - 2\Delta t \epsilon^2 \mathbf{L}) \hat{u}^{k+1} = 4\hat{u}^k - \hat{u}^{k-1} + 4\Delta t \mathbf{N}(\hat{u}^k) - 2\Delta t \mathbf{N}(\hat{u}^{k-1}) \quad (\text{second order})$$

- In practice, fourth-order schemes such as IMEX-BDF4 or LIRK4
- Nonlinear term in physical space: $\mathbf{N}(\hat{u}^k) = \mathbf{F} \mathcal{N}(\mathbf{F}^{-1} \hat{u}^k)$ with FFT matrix \mathbf{F}
- Cost per time-step: $\mathcal{O}(N \log N)$

⁴Ascher, Ruuth & Wetton, *Implicit-explicit methods for time-dependent PDEs* (1995)

■ Embryogenesis model:⁵


Equations:

$$\begin{cases} U_t = \epsilon_U^2 \Delta U + k_b f(U) V - k_d U \text{ on } \partial\Omega, \\ V_t = \epsilon_V^2 \Delta V \text{ in } \Omega, \\ \epsilon_V^2 (\nabla V \cdot n) = -k_b f(U) V + k_d U \end{cases}$$

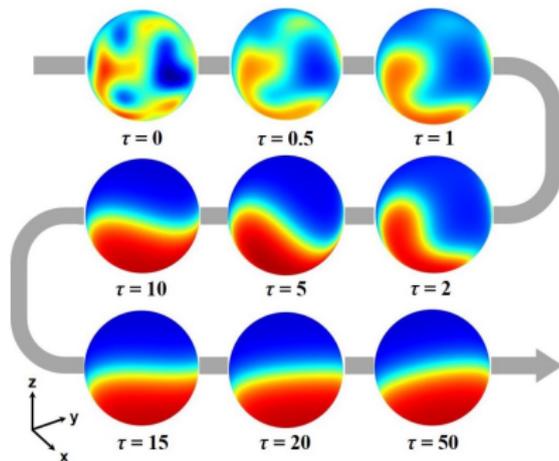
Nondimensionalization:

$$\begin{aligned} u &= k_d U / k_b V_0, \\ \tau &= k_d t, \\ \epsilon^2 &= \epsilon_U^2 / k_d \end{aligned}$$

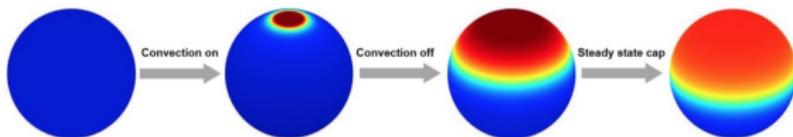
$$u_\tau = \epsilon^2 \Delta u + \mathcal{N}(u)$$

⁵Diegmiller, M., Muratov & Shvartsman, *Spherical caps in cell polarization* (2018)

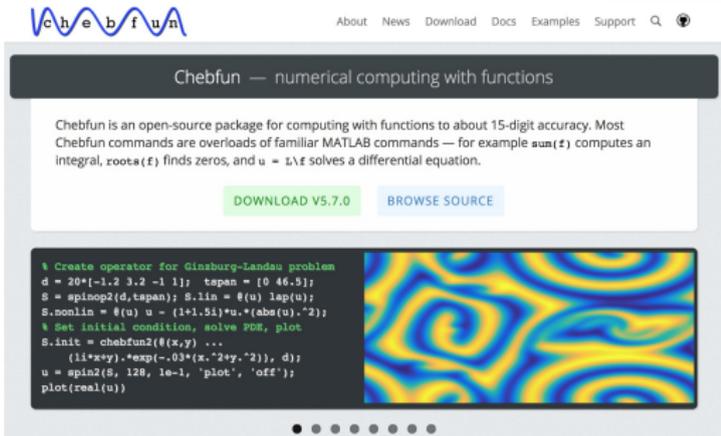
- Random initial conditions relax to a single cap



- Constant initial conditions with transient convection also relax to a single cap



- Chebfun: MATLAB package for computing to ≈ 15 digits of accuracy
- Function approximation and PDE solvers in 1D/2D/3D, on the sphere, etc.
- Led by Nick Trefethen at the University of Oxford



The screenshot shows the Chebfun website homepage. At the top, the word "chebfun" is written in a stylized, wavy font. Below it, there are navigation links: "About", "News", "Download", "Docs", "Examples", "Support", a search icon, and a GitHub icon. The main heading reads "Chebfun — numerical computing with functions". A paragraph of text describes Chebfun as an open-source package for computing with functions to about 15-digit accuracy, listing examples like `sum(f)`, `integral`, `roots(f)`, and `u = 1/f`. Below the text are two buttons: "DOWNLOAD V5.7.0" and "BROWSE SOURCE". At the bottom left, there is a code block with MATLAB code for solving a Ginsburg-Landau problem. To the right of the code is a 2D heatmap visualization of the solution, showing a complex, swirling pattern of colors (blue, yellow, red).

Aurentz, Austin,
Driscoll, Filip,
Güttel, Hale,
Hashemi, Nakatsukasa,
Platte, Townsend,
Trefethen, Wright

- Standard differential operators are local:

$$Df(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$

- It is possible to define nonlocal analogues:⁶

$$D_\delta f(x) = \int_0^\delta \frac{f(x+h) - f(x)}{h} dh$$

- Examples include fractional differential operators and integral operators
- When are they useful?
 - The phenomenon we are interested in is intrinsically nonlocal, e.g., peridynamics
 - The phenomenon is local but hard to discretize—approximating the local phenomenon with a nonlocal model, and then discretizing the latter may be easier
 - We do not know—the parameter δ gives more flexibility in the modeling process

⁶Du, *Nonlocal modeling, analysis, and computation* (2019)

- Nonlocal PDEs:

$$u_t = \epsilon^2 \mathcal{L}_\delta u + \mathcal{N}(u), \quad \mathcal{L}_\delta u(\mathbf{x}) = \int_{\mathbb{S}^2} \rho_\delta(|\mathbf{x} - \mathbf{y}|) [u(\mathbf{y}) - u(\mathbf{x})] d\Omega(\mathbf{y})$$

- Operator \mathcal{L}_δ decouples the spherical harmonic modes ($\ell \geq 0, -\ell \leq m \leq \ell$):

$$\mathcal{L}_\delta Y_\ell^m(\theta, \varphi) = \underbrace{\left(2\pi \int_{-1}^1 (P_\ell(t) - 1) \rho_\delta(\sqrt{2(1-t)}) dt \right)}_{\lambda_\delta(\ell)} Y_\ell^m(\theta, \varphi),$$

$$\mathcal{L}_0 Y_\ell^m(\theta, \varphi) = \Delta Y_\ell^m(\theta, \varphi) = -\ell(\ell + 1) Y_\ell^m(\theta, \varphi)$$

- Approximations by spherical harmonic series with $N = (n + 1)(2n + 1)$ coeffs:

$$u(t, \theta, \varphi) \approx \sum_{\ell=0}^n \sum_{m=-\ell}^{+\ell} \tilde{u}_{\ell m}(t) Y_\ell^m(\theta, \varphi)$$

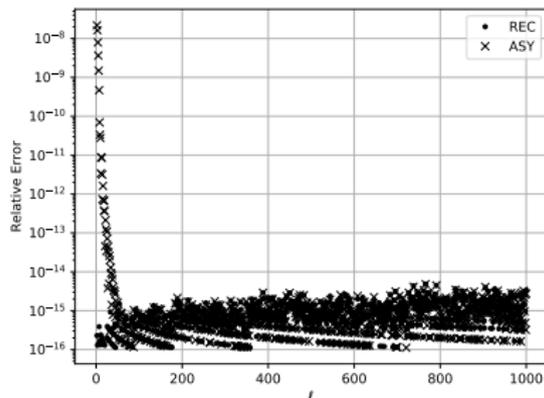
- \mathcal{L}_δ discretized⁷ with a matrix \mathbf{L}_δ acting on spherical harmonics coefficients \tilde{u}
- PDE $u_t = \epsilon^2 \mathcal{L}_\delta u + \mathcal{N}(u) \rightarrow$ system of ODEs $\tilde{u}'(t) = \epsilon^2 \mathbf{L}_\delta \tilde{u} + \mathbf{N}(\tilde{u})$

- \mathbf{L}_δ is diagonal with entries $\lambda_\delta(\ell)$:

$$\lambda_\delta(\ell) = 2\pi \int_{-1}^1 (P_\ell(t) - 1) \rho_\delta(\sqrt{2(1-t)}) dt$$

$$\rho_\delta(\sqrt{2(1-t)}) \propto \frac{1}{(1-t)^{1-\alpha}} \chi_{[0, \delta]}$$

- Computation of $\lambda_\delta(\ell)$:
modified Clenshaw–Curtis quadrature
recurrence & asymptotic formulas



⁷Slevinsky, M. & Du, A spectral method for nonlocal diffusion operators on the sphere (2018)

- PDE $u_t = \epsilon^2 \mathcal{L}_\delta u + \mathcal{N}(u) \longrightarrow$ system of ODEs $\tilde{u}'(t) = \epsilon^2 \mathbf{L}_\delta \tilde{u} + \mathbf{N}(\tilde{u})$

- Discretization with time-step Δt : $\tilde{u}^k = \tilde{u}(k\Delta t)$, $k = 0, 1, \dots$
- Large $\mathcal{O}(N)$ eigenvalues: **stiffness**, standard explicit time-stepping impractical

- **Exponential integrators** (Hochbruck & Ostermann⁸): exact \mathbf{L}_δ , numerical \mathbf{N}

$$\tilde{u}^{k+1} = e^{\Delta t \epsilon^2 \mathbf{L}_\delta} \tilde{u}^k + (\epsilon^2 \mathbf{L}_\delta)^{-1} (e^{\Delta t \epsilon^2 \mathbf{L}_\delta} - \mathbf{I}) \mathbf{N}(\tilde{u}^k) \quad (\text{first order})$$

- In practice, fourth-order schemes such as ETDRK4 (best for diagonal problems⁹)
- Nonlinear term in physical space: $\mathbf{N}(\tilde{u}^k) = \mathbf{G} \mathcal{N}(\mathbf{G}^{-1} \tilde{u}^k)$ with FST matrix \mathbf{G}
- Cost per time-step: $\mathcal{O}(N \log^2 N)$

⁸Hochbruck & Ostermann, *Exponential integrators* (2010)

⁹M. & Bootland, *Solving periodic stiff PDEs in 1D, 2D and 3D with exponential integrators* (2020)

Background

- Nonlinear advection equations on the sphere such as the barotropic vorticity equation are of significant importance in atmospheric numerical modeling

$$u_t + \frac{(\Delta^{-1}u)_\theta}{\sin\theta} u_\lambda - \frac{(\Delta^{-1}u)_\lambda}{\sin\theta} (u_\theta - 2\Omega \sin\theta) = 0$$

- A first step towards solving the shallow water & Navier–Stokes equations
- Spectral accuracy in space: spherical harmonics, RBFs, DFS method
- DFS is the only one that has $\mathcal{O}(N \log N)$ cost per time-step for N grid points

Goal

- Extend my DFS-based algorithm to solve nonlinear advection equations

Challenges

- Pole conditions—for reaction-diffusion equations, numerically satisfied; for advection equations, have to be enforced while maintaining spectral accuracy

$$\sum_{j=-m/2}^{m/2-1} \hat{u}_{j,k} = \sum_{j=-m/2}^{m/2-1} (-1)^j \hat{u}_{j,k} = 0, \quad |k| \geq 1$$

- Aliasing instabilities—for reaction-diffusion equations, Laplacian had a stabilizing effect; for advection equations, stabilization needed with, e.g., vanishing viscosity

Background

- Nonlocal models are ubiquitous in applied fields including materials science, fluid dynamics, fracture mechanics, and image analysis
- Already introduced nonlocal diffusion operators on the sphere

$$\mathcal{L}_\delta u(\mathbf{x}) = \int_{\mathbb{S}^2} \rho_\delta(|\mathbf{x} - \mathbf{y}|) [u(\mathbf{y}) - u(\mathbf{x})] d\Omega(\mathbf{y})$$

Goal

- Develop a nonlocal vector calculus on the sphere, including nonlocal surface divergence, gradient, and curl operators together with their adjoints

$$\mathcal{G}_\delta u(\mathbf{x}) = \int_{\mathbb{S}^2} [u(\mathbf{x}, \mathbf{y}) + u(\mathbf{y}, \mathbf{x})] \alpha_\delta(\mathbf{x}, \mathbf{y}) d\Omega(\mathbf{y})$$

Challenges

- Requires the use of vector spherical harmonics—expansions in vector spherical harmonics may be easily obtained from the Helmholtz–Hodge decomposition
- Nonlocal operators and their adjoints act on one- or two-point functions

$$\mathcal{G}_\delta^* \mathbf{V}(\mathbf{x}, \mathbf{y}) = \mathbf{V}(\mathbf{x}) \cdot \alpha_\delta(\mathbf{x}, \mathbf{y}) + \mathbf{V}(\mathbf{y}) \cdot \alpha_\delta(\mathbf{y}, \mathbf{x})$$

- Vector fields on manifolds are tricky to handle

Background

- Consider the following 3D Helmholtz equation,

$$\begin{aligned}
 -(\Delta + k^2) u(\mathbf{x}) &= 0, & \mathbf{x} \in \mathbb{R}^3 \setminus \bar{\Omega}, \\
 u(\mathbf{x}) &= f(\mathbf{x}), & \mathbf{x} \in \Gamma
 \end{aligned}$$

- This is a Dirichlet exterior problem whose solution is given by $u = \mathcal{S} \left[\frac{\partial u}{\partial n} \right]$ with

$$\int_{\Gamma} G(\mathbf{x}, \mathbf{y}) \left[\frac{\partial u}{\partial n} \right](\mathbf{y}) d\Gamma(\mathbf{y}) = f(\mathbf{x}), \quad \mathbf{x} \in \Gamma$$

Goals

- Design a fast hierarchical solver for high-order boundary elements on curved surfaces

Challenges

- Curved surfaces (e.g., unit sphere)—high-order polynomials need to be combined with high-order meshes (i.e., curved elements)
- Singular integrals—regularization or/and semi-analytic methods
- Dense matrices—hierarchical matrices for faster matrix-vector products

Background

- Why and when do deep networks break the curse of dimensionality?
- For a real-valued function u in \mathbb{R}^d with smoothness m and for some prescribed $\epsilon > 0$,

$$\|u - u_W\| \leq \epsilon \quad \text{with} \quad W = \mathcal{O}(\epsilon^{-\frac{d}{m}})$$

- Above result: curse of dimensionality, *i.e.*, W grows geometrically with d
- Bandlimited functions u of the form¹⁰

$$u(\mathbf{x}) = \int_{\mathbb{R}^d} G(\mathbf{x} \cdot \mathbf{y}) f(\mathbf{y}) d\mathbf{y}, \quad G \text{ is analytic, } \text{supp } f \subset [-1, 1]^d,$$

can be approximated with error ϵ by networks of size $W = \mathcal{O}(\epsilon^{-2} \log^2 \epsilon^{-1})$

- It resembles the solution to Helmholtz equation $-(\Delta + k^2)u = f$ in \mathbb{R}^d

Goal

- Study the curse of dimensionality in the solutions of high-dimensional PDEs

Challenge

- Approximation of G —for Helmholtz equation, it is in general singular

¹⁰M., Yang & Du, *Deep ReLU networks for bandlimited functions* (2020)